

An Introduction to Lie 3-Algebra

Pei-Ming Ho
Department of Physics
National Taiwan University

Nambu's Generalization of Canonical Formulation

- Rigid rotator as an example [Nambu 73]

- Hamilton-Jacobi eqs:

$$\{H, x\} = dx/dt, \quad \{H, p\} = dp/dt$$

- $\{H, F(y)\} = dF(y)/dt, \quad y = (x, p)$

- Generalization:

$$\{H, G, F(z)\} = dF(z)/dt, \quad z = (p, q, r)$$

for a 3 dim. phase space

- Conservation of phase space volume
- Invariant under canonical transfs. of H, G .

Generalization of Noncommutative Geometry

- Noncommutative space:

$$[x, y] = i\theta, \quad \text{approx. by } \{x, y\} = \theta$$

- Generalization (nonassociative space?):

$$\{x, y, z\} = \theta \quad \text{for a 3 dim. space}$$

- Physical laws deformed
- Implications to Cosmology?
- String Theory / M Theory:

B field on D-brane \rightarrow noncommutativity

C field on M5-brane \rightarrow Nambu-Poisson bracket

Lie (2-)algebra

- $H = \{ A = \sum_{a=1 \sim n} A_a T^a \}, [A, B] \in H$
- $[A, B]$ = bi-linear, skew-symmetric
- $[A, [B, C]] = [[A, B], C] + [B, [A, C]] \leftarrow$ Covariance
- $[A, [B, C]] - [B, [A, C]] = [[A, B], C] \leftarrow$ Closure

(The same Jacobi id. written differently.)

- Let $\delta_A B = [A, B]$

$$\delta_A [B, C] = [\delta_A B, C] + [B, \delta_A C]$$

$$\delta_1 \delta_2 B - \delta_2 \delta_1 B = [\delta_1, \delta_2] B$$

Commutator vs. Lie bracket

- Commutator $[A, B] = A.B - B.A$
- An *associative* algebra (rules of multiplication that satisfy associativity) is assumed.
- Jacobi identity is a result of associativity:
 $(A.B).C = A.(B.C)$
- Commutator = Lie bracket for representations of Lie algebra using matrices.
- The algebra is called the “universal enveloping Lie algebra”.

Lie 3-algebra

- $H = \{A = \sum_{a=1 \sim n} A_a T^a\}$, $[A, B, C] \in H$
- $[A, B, C]$ = tri-linear, skew-symmetric
- $[A, B, [C, D, E]] = [[A, B, C], D, E] + [C, [A, B, D], E] + [C, D, [A, B, E]]$
fundamental id. (generalized Jacobi id.)
- Let $\delta_{AB} C = [A, B, C]$
 $\delta_{AB} [C, D, E] = [\delta_{AB} C, D, E] + [C, \delta_{AB} D, E]$
 $+ [C, D, \delta_{AB} E]$

\mathcal{A}_4

- 4 generators $\{T_a\}$ ($a = 1, 2, 3, 4$)

- $[T_a, T_b, T_c] = \epsilon_{abcd} T_d$

[Filippov 85: n-Lie algebras]

- generalization of $su(2)$
- Symmetry transformation is generated by two generators:

$$\delta_{\Lambda} A = \Lambda_{ab} [T_a, T_b, A]$$

= infinitesimal $SO(4)$ rotation

Poisson bracket

- Poisson brackets are infinite dim. Lie algs.

- $\{f(x), g(x)\} = P^{ab}(x) \partial_a f(x) \partial_b g(x)$

1. Skew-symmetry

2. Jacobi identity

3. Leibniz rule (new addition):

$$\{f, gh\} = \{f, g\}h + g\{f, h\}$$

- Darboux theorem:

Locally P^{ab} is canonical for $2m$ of the n coordinates

Nambu–Poisson bracket

- Generalization of Poisson brackets

[Nambu 73, Takhtajan 94]

- $\{f, g, h\} = P^{abc} \partial_a f \partial_b g \partial_c h$

1. Skew-symmetry

2. Fundamental identity

3. Leibniz rule:

$$\{f, g, h_1 \cdot h_2\} = \{f, g, h_1\}h_2 + \{f, g, h_2\}h_1$$

- Decomposability theorem:

Locally $P^{abc} = \varepsilon^{abc}$ for 3 of the n coordinates

Phenomenology of Nonassociative Geometry

- Nonassociative space:
 $\{x, y, z\} = \theta$ for our dim. space
- Rotation and translation symmetry preserved
- Gauge transformation laws deformed
- Implications to Cosmology?
Modification of CMB spectrum?
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